TRAINING A 2 LAYER NEURAL NETWORK USING SVD-GENERATED WEIGHTS

OBJECTIVES

To train a 2 layered neural network for MNIST handwritten digit classification in a low cost:

- by adjusting the scales of weights and
- by initializing the input layer's weight
- dependent to the given data using SVD.

Preliminaries

MNIST dataset is composed of 60,000 training samples and 10,000 test samples of gray-scale handwritten digit images from 0 to 9 and their labels. An original image is of 28×28 where each pixel value varies from 0 to 255. When feeding the images as an input of the feed-forward neural network, we vectorize each image, center it at 0, and l_2 -normalize by 1. Then we concatenate all the vectors of training/test samples in a row and define it as **Input matrix X**⁰. So we have X_{train}^0 of 784 \times 60,000 and X_{test}^0 of $784 \times 10,000$. Using one-hot encoding, we define a Target matrix Y of $10 \times samplesize$ where $Y_{ij} = I\{ \text{label}_j = i - 1 \}.$

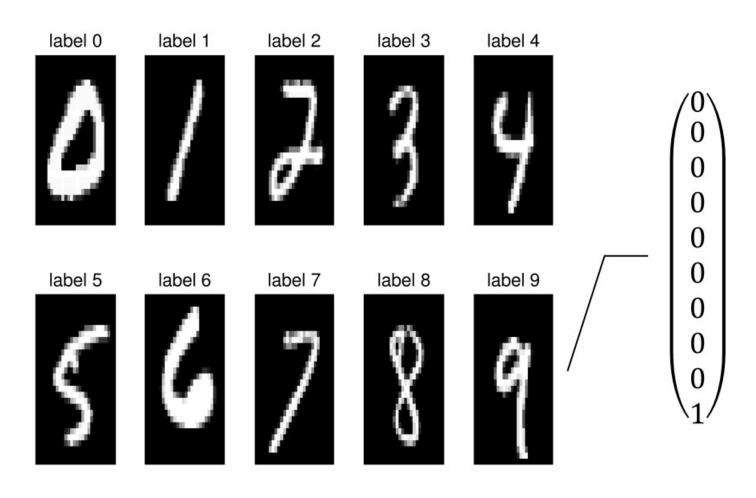


Figure 1: MNIST digit images and a target

The purpose of our 2 layered neural network is to find a set of weights and biases $\{\mathbf{W}^{l}, \mathbf{b}^{l}\}_{l=1,2}$ where $h_{\{W,b\}_{l=1,2}}(X^0)$ approximates Y with the least error.

From layer
$$l = 1$$
 to 2, we calculate

$$z^{l} = f(z^{l}) = \frac{1}{1 + exp(-z^{l})}.$$

f is an (sigmoid) activation function having the property f' = f * (1 - f). Then we put $h_{\{W,b\}_{l=1\,2}}(x^0) = x^2.$

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To estimate the error between x^2 and y, we define a loss function L called Cross Entropy(CE). Given a pair (x^0, y) , $L(\{W^l, b^l\}_{l=1,2})$ is defined as

$$\sum_{i=1}^{52} \left(y_i \log x_i^2 + (1 - y_i) \log \left(1 - x_i^2 \right) \right).$$
 (2)

We train $\{W^l, b^l\}_{l=1,2}$ by Gradient descent method. Using back propagation algorithm, $\frac{\partial L}{\partial W_{ij}^l}$ and $\frac{\partial L}{\partial W_{ii}^l}$ are formulated as below:

$$\begin{cases} \frac{\partial}{\partial W_{ij}^{l}} L\left(\{W^{l}, b^{l}\}_{l=1,2}\right) = \frac{\partial L}{\partial z_{i}^{l}} x_{j}^{l-1} &, \text{ for } l=2,1, \\ \frac{\partial}{\partial b_{i}^{l}} L\left(\{W^{l}, b^{l}\}_{l=1,2}\right) = \frac{\partial L}{\partial z_{i}^{l}} &, \text{ for } l=2,1. \end{cases}$$
(3)
$$\frac{\partial L}{\partial z_{i}^{l}} = \begin{cases} x_{i}^{l} - y_{i} &, \text{ if } l=2, \\ z_{j=1}^{s_{l+1}} W_{ji}^{l+1} \frac{\partial L}{\partial z_{j}^{l+1}} * \left(x_{i}^{l}(1-x_{i}^{l})\right) &, \text{ if } l=1. \end{cases}$$
(4)

INSPIRATION

We initialize W_{ij}^l to be mean 0, and sharing the constant variance among layers l = 1, 2.[1] And let the bias terms $b_k^1 = 0$, and $b_k^2 = -\frac{1}{2} \sum_j W_{kj}^2 \approx 0$. Then we can estimate the **expectation of the norm** square of z^1 .

If
$$W^{l+1}$$
 and x^{l} are independent,

$$E\left\|z^{1}\right\|^{2} = s_{1} Var\left[W^{1}\right] E\left[\left\|x^{0}\right\|^{2}\right], \quad (5)$$

2 if W^{l+1} and x^l are the same,

$$z^{1} \|^{2} = s_{0} s_{1} Var \left[W^{1} \right] \| x^{0} \|^{2}.$$
 (6)

When we fix the Frobenius norm of weights while training-(*), 1 and 2 are the minimum and maximum quantity of $||z^1||^2$, respectively. So, we set the dependency ratio between W^1 and x^0 as

$$dep = \frac{\|z^1\|_{\text{obs}}^2 - s_1 \|W^1\|_{\text{Fro}}^2 / (s_0 s_1)}{s_0 s_1 \|W^1\|_{\text{Fro}}^2 / (s_0 s_1)}.$$
 (7)

Note that we use $Var[W^{1}] = ||W^{1}||_{\text{Fro}}^{2}/(s_{0}s_{1})$, if $E[W^1] = 0.$

By experiments, we have seen $E[W^1] = 0$ and this dependent ratio getting increased while training. By (*), this implies W^1 is getting similar to x^0 while training.

Then what if we put the input layer's weight much close to our given training data? In this idea, we put W^1 using the principal components from SVD on the training matrix.

Let X^0 be the whole training input matrix. By SVD, $X^0 = U\Sigma V^T$ where U, Σ are of 784×784 , and V^T is of 784 \times 60,000. Choose $s_1 \leq r =$ $rank(X^0)$. Let \hat{I} and $\hat{\Sigma}^{-1}$ be $s_1 \times 784$ matrices only containing the diagonal elements 1 and σ_{ii}^{-1} , respectively. And say $Z^1 = W^1 X^0$. Then we can think of 2 types of W^1 and their $E\left[\|z^1\|^2\right]$. •An o $\|Z^1\|_{\text{Fro}}^2 = d_1^2 \sum_{i=1}^{s_1} \sigma_{ii}^2 \therefore d_1 = \sqrt{\frac{s_1(1+784*dep)Var[W^1]}{\sum_{i=1}^{s_1} \sigma_{ii}^2/60,000}}.$ **2** A scaled matrix multiplied by d_2

||Z $\therefore d$ Also, we can consider applying SVD on each label subset. We call them as $W^{1,\bullet,\text{each}}$.

Weig $W^{1,\mathrm{r}}$ $W^{1,0}$ $W^{1,0}$ $W^{1,\mathrm{se}}$ $W^{1,\mathrm{se}}$

METHODS

orthogonal matrix multiplied by
$$d_1$$

 $W^{1,\text{orth, whole}} = d_1 * \hat{I} U^T,$ (8)

$$W^{1,\text{scale, whole}} = d_2 * \hat{\Sigma}^{-1} U^T, \qquad (9)$$

$$Z^{1} \|_{\text{Fro}}^{2} = d_{2}^{2} * s_{1}.$$

$$d_{2} = \sqrt{60,000 * (1 + 784 * dep) Var [W^{1}]}.$$

RESULTS

Experiments where $s_1 = 100$ and $Var[W^1] = 0.09$.

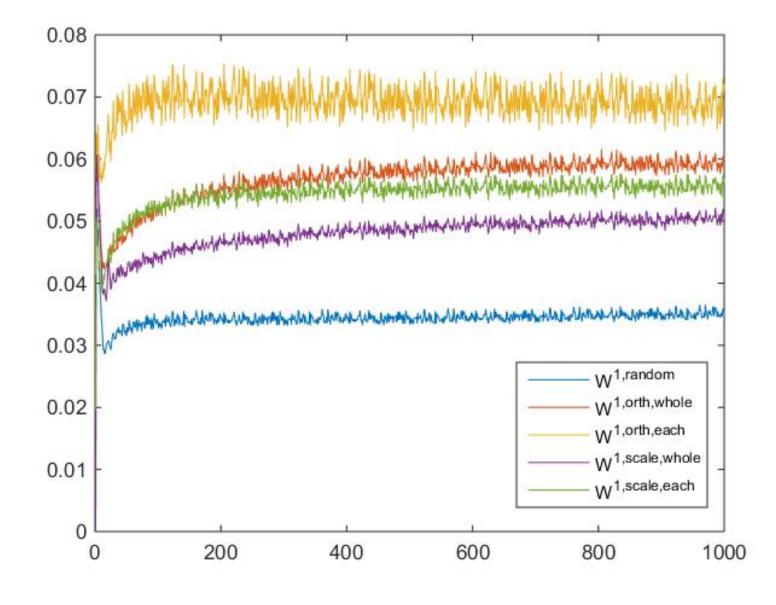


Figure 2: Dependency change while training

Table 1: Performance of each initialization after 5 epochs

ght Type	Loss Tra	ain Accuracy Te	st Accuracy
random	0.71	91.67 %	90.98 %
orth, whole	0.63	93.00~%	91.39~%
orth, each	0.59	94.67~%	93.03~%
scale, whole	0.70	93.00~%	90.90~%
scale, each	0.62	94.00~%	92.73~%

In general, orthogonal matrix of each class showed the best performance. There was no improvement of scaling each row by singular values. But the performance was better as the initial dependency of weight matrix with input data gets bigger. By the way, the computational cost of applying SVD on a $m \times n$ matrix is $O(m^2n)$ floating-point operations (flops), assuming that $m \leq n$. So, applying SVD on whole data set has the same computational cost with applying SVD on 10 divided subsets.

We can consider

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CONTACT INFORMATION



CONCLUSION

FURTHER STUDIES

• assuming the linearity of f near $0(x = f(z) \approx \frac{1}{4}z + \frac{1}{2})$. And try to estimate the expectation of the norm square of x^1 and so on, • fixing W^1 , and so train a NN without updating W^1 and reduce computational cost.

REFERENCES

[1] Xavier Glorot, Yoshua Bengio. Understanding the difficulty of training deep feedforward neural networks. Proceedings of the Thirteenth International Conference on Artificial Intelligence and Statistics, PMLR 9:249-256, 2010.

[2] Adam Gibson, Josh Patterson. Deep Learning : A Practitioner's Approach. O'Reilly Media,

[3] Unsupervised Feature Learning and Deep Learning Tutorial http://ufldl.stanford.edu/tutorial/

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